ShowAnafiLog



Many thanks to all contributors and testers. It was and is still fun to work with you together. Happy flying!

Initiated and supported by **Parrot Pilots Drone Forum**

Summary

"ShowAnafiLog" is an application to show JSON log files and Black-Box files from Parrot's "Anafi" quad-copter in a readable format, display charts from selected data columns and convert JSON logs into KML flight tracks, GPX files or CSV files for other usage.

Installation

No installation needed, this is a portable application. But you need write access to the directory where the application located. "ShowAnafiLog" will store its settings in an XML file there.

Usage

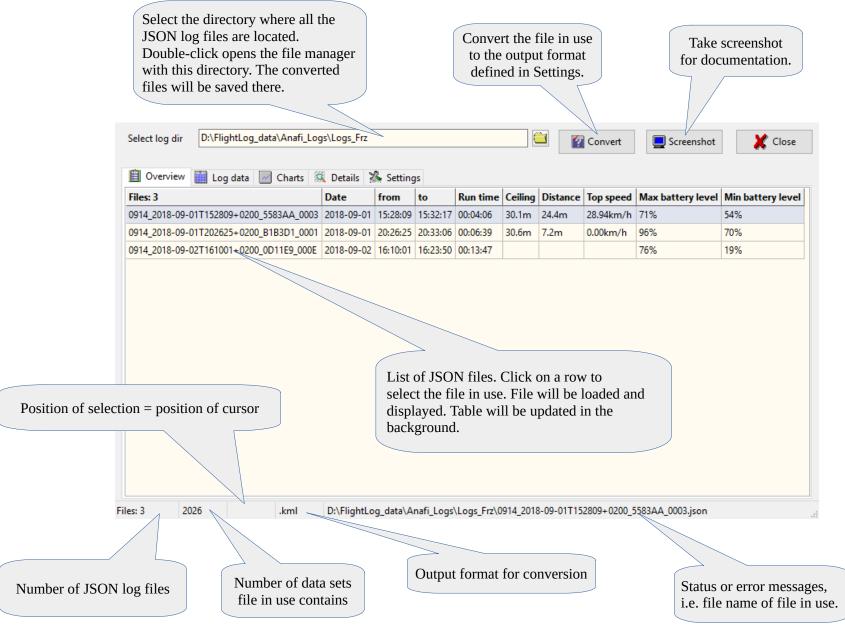
Retrieve flight logs (*.json) from your controller device and save it in a directory on your PC.

Open this directory or simply drop it to the application. A list of JSON log files will be created (see Overview) and the last file in the list will be loaded. You can select any file in the list to load and display it in the other pages (Log data, Charts, Details).

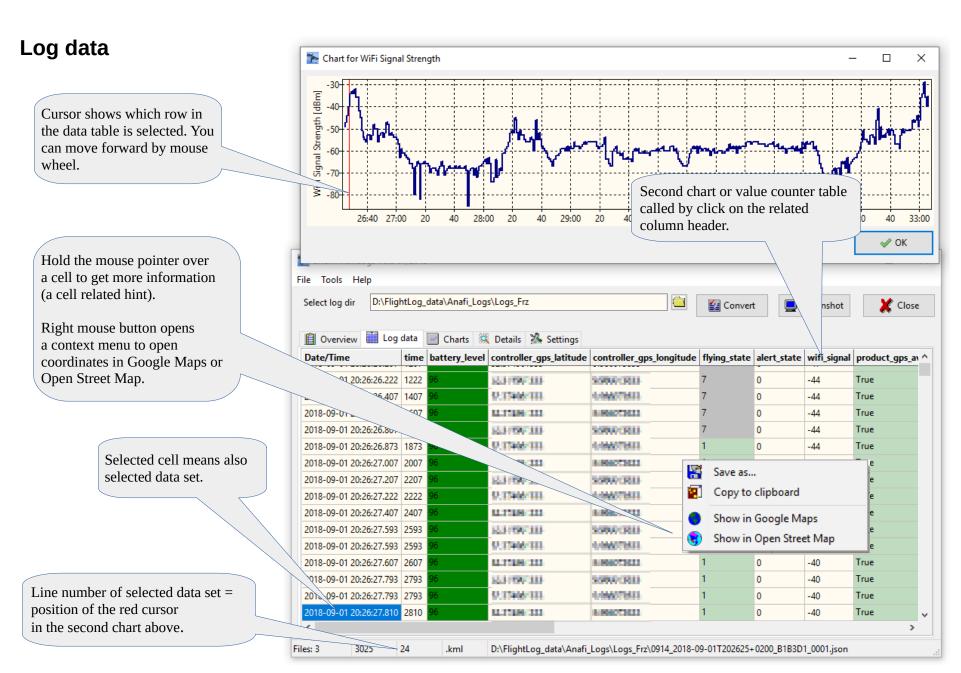
Enjoy.

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Overview



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Chart altitude

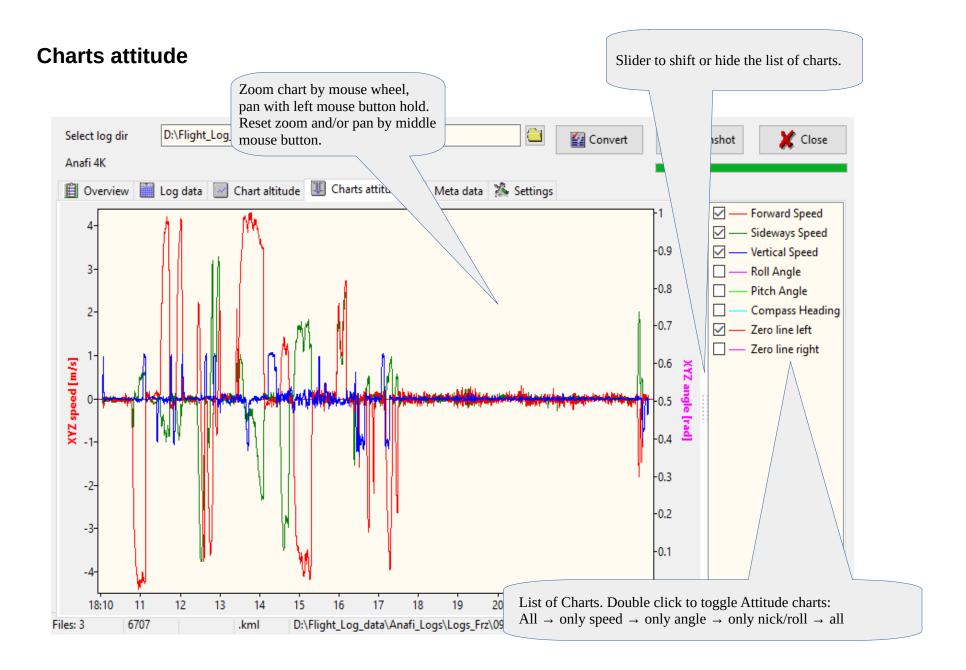
Zoom chart by mouse wheel, pan with left mouse button hold, horizontal cursor by Ctrl-key. Reset zoom and/or pan by middle mouse button.



Filled chart shows the altitude relative to take off location.

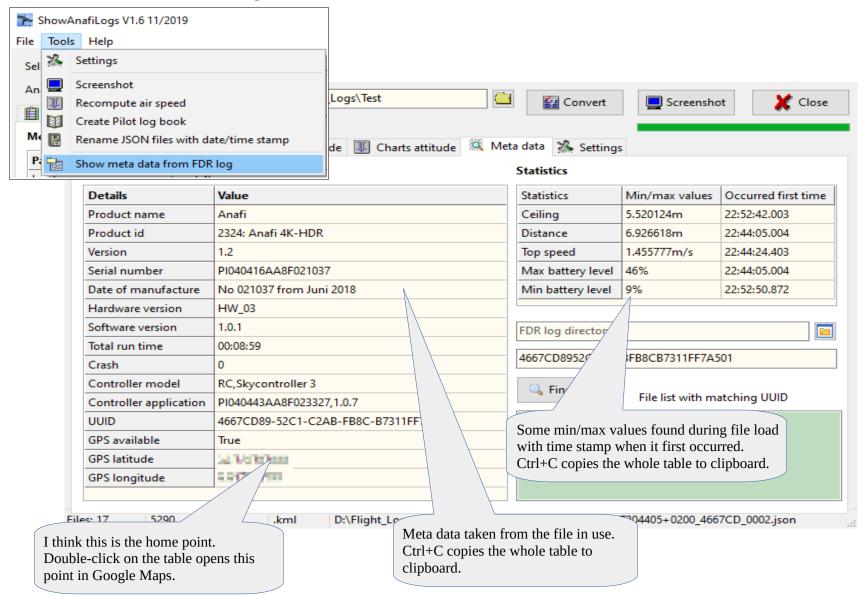
Status message about a former saved file.

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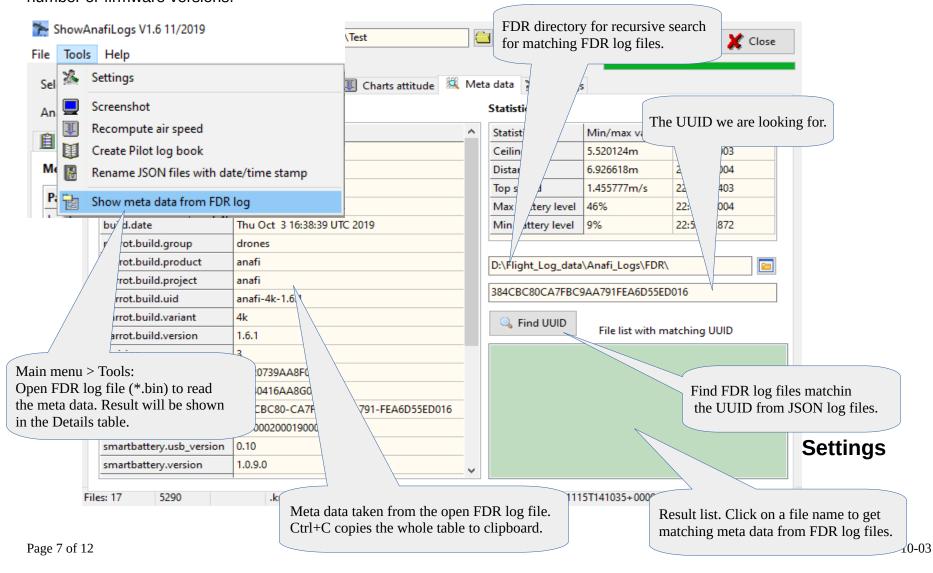
Meta data from JSON log file

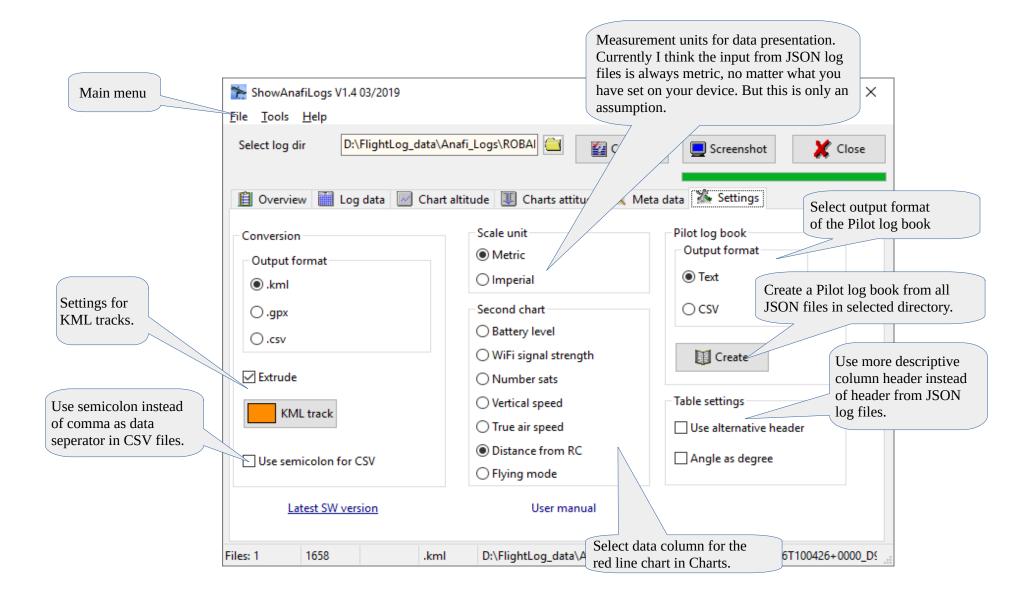


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Metadata from FDR log files

Log files in the FDR folder contains more detailed data compared to JSON log files but it is an undocumented binary format. Thus, the files keep their secrets. But some of the meta data at the beginning of the files are readable such as battery serial number or firmware versions.





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Internals

 $See \ also: \underline{https://developer.parrot.com/docs/olympe/arsdkng_ardrone3_piloting.html}$

flying_state	Meaning	Remarks, internal naming		
0	Landed	Landed		
1	Taking Off	Taking Off		
2	Hovering	Hovering		
3	Flying	Flying		
4	Landing	Landing		
5	Emergency	Emergency		
	User take off state. Waiting for user action to take			
6	off	User takeoff		
7	Motor ramping	Motor ramping		
8	Emergency landing state. Drone autopilot has	Emergency landing		
	detected defective sensor(s). Only Yaw argument			
	in PCMD is taken into account. All others flying			
	commands are ignored.			

alert_state	Meaning	Remarks, internal naming	
0	No alert	none	
1	Normal flight	user	
		cut out, if something hit the	
2	Anafi shut down propeller		
3	Battery level crucial critical battery		
4	Battery level low low battery		
5	Flight angle too high	too much angle (>70°)	
6	Almost empty battery alert empty battery		
7	Magnetometer is disturbed by a magnetic element magneto_pertubation		
8	Local terrestrial magnetic field is too weak magneto_low_earth_field		

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product_gps_position_error	Meaning	Remarks, internal naming		
0	No error	Seems to be always 0		
1	Not in outdoor mode	Possibly not used		
2	GPS not fixed	Possibly not used		
3	Compass not calibrated	Possibly not used		

flip_type	Meaning	Remarks, internal naming
0	None	Seems to be always 0
1	Front	Not used
2	Back	Not used
3	Right	Not used
4	Left	Not used

Colors to indicate quality:

Number of sats	Color
>10	green
11 to 5	orange
<5	red

Battery level	Color
>50%	green
50% to 25 %	orange
<25%	red

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Columns in "Log data" tab:

				Metric/	
Index	Header	Description	Unit	Imperial	Conversion
0	Date/Time	Computed from Date/Time in Meta data plus Time since	date/time		
		boot			
1	time		ms		
2	battery_level	J 0	%		
3	controller_gps_latitude	Controller latitude	lat		
4	controller_gps_longitude	Controller longitude	lon		
5	flying_state	Flying mode	enum		
6	alert_state	Alert state	enum		
7	wifi_signal	WiFi signal strength	dBm		
8	product_gps_available	Anafi GPS lock	bool		
9	product_gps_longitude	Anafi Longitude	lon		
10	product_gps_latitude	Anafi Latitude	lat		
11	product_gps_position_err	Anafi GPS error	enum		
	or				
12	product_gps_sv_number	Number of sats	#		
13	speed_vx	1	m/s	m/s – ft/s	
14	speed_vy	J 1	m/s	m/s – ft/s	
15	speed_vz	1	m/s	m/s – ft/s	
16	angle_phi	Attitude – Roll Angle	rad		rad - ° +/-180
17	angle_theta	0	rad		rad - ° +/-180
18	angle_psi	1 0	rad		rad - ° 0360
19	altitude	Altitude relative to take off	m ft	m – ft	
20	flip_type	1 31	enum		
21	speed	True air speed	m/s	m/s - ft/s	m/s - km/h / ft/s -
					mph
22	DIST	Distance Anafi to RC, computed from coordinates	m	m – ft	m – km / ft – mi

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Output format CSV Pilot log book:

Index	Header
0	Serial number
1	Date
2	From
3	То
4	Duration
5	Ceiling
6	Distance
7	Route
8	Top speed
9	Max battery level
10	Min battery level
11	Location
12	GPS fix at start

Disclaimer

This software is freeware. You can use this software royalty-free for private and commercial purposes.

Use this application on your own risk.

There is no guaranty for correctness and/or completeness of the results of the evaluation of flight log data or interpretation of the values in the flight logs.

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